

Bayesian Linear Regression

Sudipto Banerjee¹ and Andrew O. Finley²

¹ Biostatistics, School of Public Health, University of Minnesota, Minneapolis, Minnesota, U.S.A.

² Department of Forestry & Department of Geography, Michigan State University, Lansing Michigan, U.S.A.

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- Linear regression is, perhaps, *the* most widely used statistical modelling tool.
- It addresses the following question: How does a quantity of primary interest, y , vary as (depend upon) another quantity, or set of quantities, \mathbf{x} ?
- The quantity y is called the *response* or *outcome variable*. Some people simply refer to it as the *dependent variable*.
- The variable(s) \mathbf{x} are called *explanatory variables*, *covariates* or simply *independent variables*.
- In general, we are interested in the conditional distribution of y , given \mathbf{x} , parametrized as $p(y | \theta, \mathbf{x})$.

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- Typically, we have a set of *units* or *experimental subjects* $i = 1, 2, \dots, n$.
- For each of these units we have measured an outcome y_i and a set of explanatory variables $\mathbf{x}'_i = (1, x_{i1}, x_{i2}, \dots, x_{ip})$.
- The first element of \mathbf{x}'_i is often taken as 1 to signify the presence of an "intercept".
- We collect the outcome and explanatory variables into an $n \times 1$ vector and an $n \times (p + 1)$ matrix:

$$\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}; \quad \mathbf{X} = \begin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1p} \\ 1 & x_{21} & x_{22} & \dots & x_{2p} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & x_{n1} & x_{n2} & \dots & x_{np} \end{bmatrix} = \begin{pmatrix} \mathbf{x}'_1 \\ \mathbf{x}'_2 \\ \vdots \\ \mathbf{x}'_n \end{pmatrix}.$$

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- The linear model is the most fundamental of all serious statistical models underpinning:
 - ANOVA: y_i is continuous, x_{ij} 's are *all* categorical
 - REGRESSION: y_i is continuous, x_{ij} 's are continuous
 - ANCOVA: y_i is continuous, x_{ij} 's are continuous for some j and categorical for others.

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- The Bayesian or hierarchical linear model is given by:

$$y_i | \mu_i, \sigma^2, \mathbf{X} \stackrel{\text{ind}}{\sim} N(\mu_i, \sigma^2); \quad i = 1, 2, \dots, n;$$

$$\mu_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} = \mathbf{x}'_i \boldsymbol{\beta}; \quad \boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_p);$$

$$\boldsymbol{\beta}, \sigma^2 | \mathbf{X} \sim p(\boldsymbol{\beta}, \sigma^2 | \mathbf{X}).$$
- Unknown parameters include the regression parameters and the variance, i.e. $\theta = \{\boldsymbol{\beta}, \sigma^2\}$.
- $p(\boldsymbol{\beta}, \sigma^2 | \mathbf{X}) \equiv p(\theta | \mathbf{X})$ is the joint *prior* on the parameters.
- We assume \mathbf{X} is observed without error and all inference is conditional on \mathbf{X} .
- We suppress dependence on \mathbf{X} in subsequent notation.

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- Specifying $p(\boldsymbol{\beta}, \sigma^2)$ completes the hierarchical model.
- All inference proceeds from $p(\boldsymbol{\beta}, \sigma^2 | \mathbf{y})$
- With no prior information, we specify

$$p(\boldsymbol{\beta}, \sigma^2) \propto \frac{1}{\sigma^2} \text{ or equivalently } p(\boldsymbol{\beta}) \propto 1; \quad p(\log(\sigma^2)) \propto 1.$$
- The above is **NOT** a probability density (they do not integrate to any finite number). So why is it that we are even discussing them?
- Even if the priors are *improper*, as long as the resulting posterior distributions are valid we can still conduct legitimate statistical inference on them.

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Computing the posterior distribution

- Strategy: Factor the joint posterior distribution for β and σ^2 as:

$$p(\beta, \sigma^2 | \mathbf{y}) = p(\beta | \sigma^2, \mathbf{y}) \times p(\sigma^2 | \mathbf{y}).$$

- The *conditional posterior* distribution of β , given σ^2 :

$$\beta | \sigma^2, \mathbf{y} \sim N(\hat{\beta}, \sigma^2 \mathbf{V}_\beta),$$

where, using some algebra, one finds

$$\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} \quad \text{and} \quad \mathbf{V}_\beta = (\mathbf{X}'\mathbf{X})^{-1}.$$

- The *marginal posterior* distribution of σ^2 : Let $k = (p + 1)$ be the number of columns of \mathbf{X} .

$$\sigma^2 | \mathbf{y} \sim IG\left(\frac{n-k}{2}, \frac{(n-k)s^2}{2}\right),$$

where

$$s^2 = \frac{1}{n-k}(\mathbf{y} - \mathbf{X}\hat{\beta})'(\mathbf{y} - \mathbf{X}\hat{\beta})$$

is the classical unbiased estimate of σ^2 in the linear regression model.

- The *marginal posterior* distribution $p(\beta | \mathbf{y})$, averaging over σ^2 , is *multivariate t* with $n - k$ degrees of freedom. But we rarely use this fact in practice.
- Instead, we *sample* from the posterior distribution.

Algorithm for sampling from the posterior distribution

- We draw samples from $p(\beta, \sigma^2 | \mathbf{y})$ by executing the following steps:

- Step 1: Compute $\hat{\beta}$ and \mathbf{V}_β .

- Step 2: Compute s^2 .

- Step 3: Draw M samples from $p(\sigma^2 | \mathbf{y})$:

$$\sigma^{2(j)} \sim IG\left(\frac{n-k}{2}, \frac{(n-k)s^2}{2}\right), \quad j = 1, \dots, M$$

- Step 4: For $j = 1, \dots, M$, draw $\beta^{(j)}$ from $p(\beta | \sigma^{2(j)}, \mathbf{y})$:

$$\beta^{(j)} \sim N(\hat{\beta}, \sigma^{2(j)} \mathbf{V}_\beta)$$

- The marginal distribution of each individual regression parameter β_j is a non-central univariate t_{n-p} distribution. In fact,

$$\frac{\beta_j - \hat{\beta}_j}{s\sqrt{\mathbf{V}_{\beta;jj}}} \sim t_{n-p}.$$

The 95% credible interval for each β_j is constructed from the quantiles of the t -distribution. This exactly coincides with the 95% classical confidence intervals, but the interpretation is direct: the probability of β_j falling in that interval, given the observed data, is 0.95.

- Note: an intercept only linear model reduces to the simple univariate $N(\bar{y} | \mu, \sigma^2/n)$ likelihood, for which the marginal posterior of μ is:

$$\frac{\mu - \bar{y}}{s/\sqrt{n}} \sim t_{n-1}.$$

- Suppose we have observed the new predictors $\tilde{\mathbf{X}}$, and we wish to predict the outcome $\tilde{\mathbf{y}}$.
- If β and σ^2 were known exactly, the random vector $\tilde{\mathbf{y}}$ would follow $N(\tilde{\mathbf{X}}\beta, \sigma^2\mathbf{I})$.
- But we do not know model parameters, which contribute to the uncertainty in predictions.
- Predictions are carried out by sampling from the *posterior predictive* distribution, $p(\tilde{\mathbf{y}} | \mathbf{y})$
 - 1 Draw $\{\beta^{(j)}, \sigma^{2(j)}\} \sim p(\beta, \sigma^2 | \mathbf{y}), j = 1, 2, \dots, M$
 - 2 Draw $\tilde{\mathbf{y}}^{(j)} \sim N(\tilde{\mathbf{X}}\beta^{(j)}, \sigma^{2(j)}\mathbf{I}), j = 1, 2, \dots, M.$

- Predictive Mean and Variance (conditional upon σ^2):

$$E(\tilde{\mathbf{y}} | \sigma^2, \mathbf{y}) = \tilde{\mathbf{X}}\hat{\beta}$$

$$\text{var}(\tilde{\mathbf{y}} | \sigma^2, \mathbf{y}) = (\mathbf{I} + \tilde{\mathbf{X}}\mathbf{V}_\beta\tilde{\mathbf{X}}')\sigma^2.$$

- The posterior predictive distribution, $p(\tilde{\mathbf{y}} | \mathbf{y})$, is a *multivariate t* distribution, $t_{n-p}(\tilde{\mathbf{X}}\hat{\beta}, s^2(\mathbf{I} + \tilde{\mathbf{X}}\mathbf{V}_\beta\tilde{\mathbf{X}}'))$.

Incorporating prior information

$$y_i | \mu_i, \sigma^2 \stackrel{ind}{\sim} N(\mu_i, \sigma^2); \quad i = 1, 2, \dots, n;$$

$$\mu_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} = \mathbf{x}'_i \boldsymbol{\beta}; \quad \boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_p);$$

$$\boldsymbol{\beta} | \sigma^2 \sim N(\boldsymbol{\beta}_0, \sigma^2 \mathbf{R}_\beta); \quad \sigma^2 \sim IG(a_\sigma, b_\sigma),$$

where \mathbf{R}_β is a *fixed* correlation matrix. Alternatively,

$$y_i | \mu_i, \sigma^2 \stackrel{ind}{\sim} N(\mu_i, \sigma^2); \quad i = 1, 2, \dots, n;$$

$$\mu_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} = \mathbf{x}'_i \boldsymbol{\beta}; \quad \boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_p);$$

$$\boldsymbol{\beta} | \Sigma_\beta \sim N(\boldsymbol{\beta}_0, \Sigma_\beta); \quad \Sigma_\beta \sim IW(\nu, \mathbf{S}); \quad \sigma^2 \sim IG(a_\sigma, b_\sigma),$$

where Σ_β is a *random* covariance matrix.

- The Gibbs sampler: If $\boldsymbol{\theta} = (\theta_1, \dots, \theta_p)$ are the parameters in our model, we provide a set of initial values $\boldsymbol{\theta}^{(0)} = (\theta_1^{(0)}, \dots, \theta_p^{(0)})$ and then performs the j -th iteration, say for $j = 1, \dots, M$, by updating successively from the *full conditional* distributions:

$$\theta_1^{(j)} \sim p(\theta_1^{(j)} | \theta_2^{(j-1)}, \dots, \theta_p^{(j-1)}, \mathbf{y})$$

$$\theta_2^{(j)} \sim p(\theta_2^{(j)} | \theta_1^{(j)}, \theta_3^{(j)}, \dots, \theta_p^{(j-1)}, \mathbf{y})$$

$$\vdots$$

(the generic k^{th} element)

$$\theta_k^{(j)} \sim p(\theta_k^{(j)} | \theta_1^{(j)}, \dots, \theta_{k-1}^{(j)}, \theta_{k+1}^{(j)}, \dots, \theta_p^{(j-1)}, \mathbf{y})$$

$$\vdots$$

$$\theta_p^{(j)} \sim p(\theta_p^{(j)} | \theta_1^{(j)}, \dots, \theta_{p-1}^{(j)}, \mathbf{y})$$

- In principle, the Gibbs sampler will work for extremely complex hierarchical models. The only issue is sampling from the full conditionals. They may not be amenable to easy sampling – when these are not in closed form. A more general and extremely powerful - and often easier to code - algorithm is the Metropolis-Hastings (MH) algorithm.
- This algorithm also constructs a Markov Chain, but does not necessarily care about full conditionals.
- Popular approach: Embed Metropolis steps within Gibbs to draw from full conditionals that are not accessible to directly generate from.