

# Hierarchical Modeling for Spatio-temporal Data

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Specification:

- Again point-referenced vs. areal unit data
- Continuous time vs. discretized time

⇒ association in space, association in time

For point-referenced data, t continuous, Gaussian

$$y(\mathbf{s}, t) = \mu(\mathbf{s}, t) + w(\mathbf{s}, t) + \epsilon(\mathbf{s}, t)$$

non-Gaussian data,  $g(E[y(\mathbf{s}, t)]) = \mu(\mathbf{s}, t) + w(\mathbf{s}, t)$

**Don't** treat time as a third coordinate ( $\mathbf{s}, t$ )

$$Cov(y(\mathbf{s}, t), y(\mathbf{s}', t')) = C(\mathbf{s} - \mathbf{s}', t - t')$$

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- **Separable form:**

$$C(\mathbf{s} - \mathbf{s}', t - t') = \sigma^2 \rho_1(\mathbf{s} - \mathbf{s}'; \phi_1) \rho_2(t - t'; \phi_2)$$

- **Nonseparable form:**

- Sum of independent separable processes
- Mixing of separable covariance functions
- Spectral domain approaches

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- Time discretized,  $y_t(\mathbf{s}), t = 1, 2, \dots, T$
- Type of data: time series or cross-sectional

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- **Modeling:**  $y_t(\mathbf{s}) = \mu_t(\mathbf{s}) + w_t(\mathbf{s}) + \epsilon_t(\mathbf{s})$ , or perhaps  $g(E[y_t(\mathbf{s})]) = \mu_t(\mathbf{s}) + w_t(\mathbf{s})$
- For  $\epsilon_t(\mathbf{s})$ , i.i.d.  $N(0, \tau_t^2)$
- For  $w_t(\mathbf{s})$ 
  - $w_t(\mathbf{s}) = \alpha_t + w(\mathbf{s})$
  - $w_t(\mathbf{s})$  independent for each  $t$
  - $w_t(\mathbf{s}) = w_{t-1}(\mathbf{s}) + \eta_t(\mathbf{s})$ , independent spatial process innovations

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Dynamic spatiotemporal models

## Measurement Equation

$$y(\mathbf{s}, t) = \mu(\mathbf{s}, t) + \epsilon(\mathbf{s}, t); \quad \epsilon(\mathbf{s}, t) \stackrel{ind}{\sim} N(0, \sigma_\epsilon^2).$$

$$\mu(\mathbf{s}, t) = \mathbf{x}(\mathbf{s}, t)' \tilde{\beta}(\mathbf{s}, t).$$

$$\tilde{\beta}(\mathbf{s}, t) = \beta_t + \beta(\mathbf{s}, t)$$

## Transition Equation

$$\beta_t = \beta_{t-1} + \eta_t, \quad \eta_t \stackrel{ind}{\sim} N_p(\mathbf{0}, \Sigma_\eta)$$

$$\beta(\mathbf{s}, t) = \beta(\mathbf{s}, t-1) + \mathbf{w}(\mathbf{s}, t).$$

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